



$$u(n, t) = w(n, t) + Q(n, t) \quad (1)$$

$$\text{and } u_{nn} = u_t + \Delta \quad \begin{matrix} \text{using} \\ u=w+Q \end{matrix} \quad (w_{nn} + Q_{nn}) = w_t + Q_n$$

$$w_{nn} = w_t + \Delta - Q_n$$

$$\text{at } n=0, \Delta=0 \Rightarrow n-Q(n)=0 \Rightarrow Q(n)=n$$

$$\text{at } t=0 \Rightarrow u(0, t) = w(0, t) + Q(0) =$$

$$u(\tau, t) = 1 = w(\tau, t) + Q(\tau).$$

$$w(0, t) = 0, w(\tau, t) = 0 \quad \text{at } t=0 \text{ and at } \tau \text{ (using boundary conditions)}$$

$$\text{Or } \rightarrow Q(0) = 1, Q(\tau) = 1$$

$$\text{at } n=0 \Rightarrow u(n, 0) = e^n = w(n, 0) + Q(n).$$

$$w(n, 0) = e^n - Q(n) \quad \text{at } n=0$$

$$\text{Given } Q(0) = 1, Q(\tau) = 1 \quad \text{at } n=0, Q(n) = \text{constant} = Q_0$$

$$Q(n) = \int n \, dn = \frac{1}{2} n^2 + C_1$$

$$\text{by I.D. } \rightarrow Q(0) = C_1 = 1$$

$$Q(\tau) = \frac{1}{2} (\tau)^2 + C_1 \cdot \tau + 1 = \frac{\tau^2}{2} + \tau C_1 + 1$$

$$\Rightarrow \tau C_1 = 1 - \frac{\tau^2}{2} = -\frac{\tau^2}{2} \Rightarrow C_1 = -\frac{\tau^2}{2}$$

$$Q(n) = \frac{1}{2} n^2 - \frac{\tau^2}{2} n + 1$$

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$$\text{b) } \rightarrow Q(0) = c_1 = 1$$

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$$Q(n) = \frac{1}{q}(n) + c_1 \cdot r + l = \frac{n}{6} + rc_1 + l = \frac{n}{6} + pc_1 + l =$$

$$\frac{v}{c} + pc_1 = l$$

$$\Rightarrow rc_1 = l - \frac{v}{c} = -\frac{v}{c} \Rightarrow c_1 = -\frac{v}{rc} \quad] .$$

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$$Q(n) = \frac{1}{6}n^c - \frac{v}{rc}n + l$$